Control Program (MCP) running on one or more Instruction Processors (IPs) 17. The designations OS and MCP will be used herein interchangeably. The computer system 10 further includes an Input/Output Module (IOM) 12 for communicating with peripheral devices in a well-known manner. The IOM 12 includes a Task Control Unit (TCU) 18 which is responsible for managing task switching and events. The TCU 18 is a Special Purpose Processor (SPP) controlled by TCU microcode 13. Throughout the description herein, the designations TCU and SPP will be used interchangeably and will denote hardware or microcode or both in accordance with the context.

The IP 17 and IOM 12 provide hardware support 14 for function calls over a bi-directional interface 15. This interface is hardware dependent having the following minimal requirements. The interface 14 and 15 between the OS and SPP provides a path which permits the OS to pass data to the SPP and synchronously receive result data generated by the SPP. Further, this interface allows repeated uses of the function call. Numerous types of data exchange mechanisms suitable for use by the present invention are included in numerous types of computer systems, as is well known in the art.

While it is not necessary for this interface to be synchronous for all implementations, to do so allows the interface to be implemented as a function call. The minimum requirements for this interface is to provide a path and mechanism between the OS and SPP to exchange data.

In accordance with the invention, MCP 11 and TCU microcode 13 include a TCU_EXCHANGE_FEATURES function 16 providing an exchange protocol between MCP and TCU microcode that facilitates phasing in features that depend on particular MCP and TCU microcode functionality. The form of the communication path between the OS and SPP (MCP 11 and TCU microcode 13) is a function call by the OS utilizing Hardware Support For Function Calls 14 in